

Hands on Model Use Ahead



Load model: Schelling Segregation.alp

A Model to Examine the Emergence of Segregation

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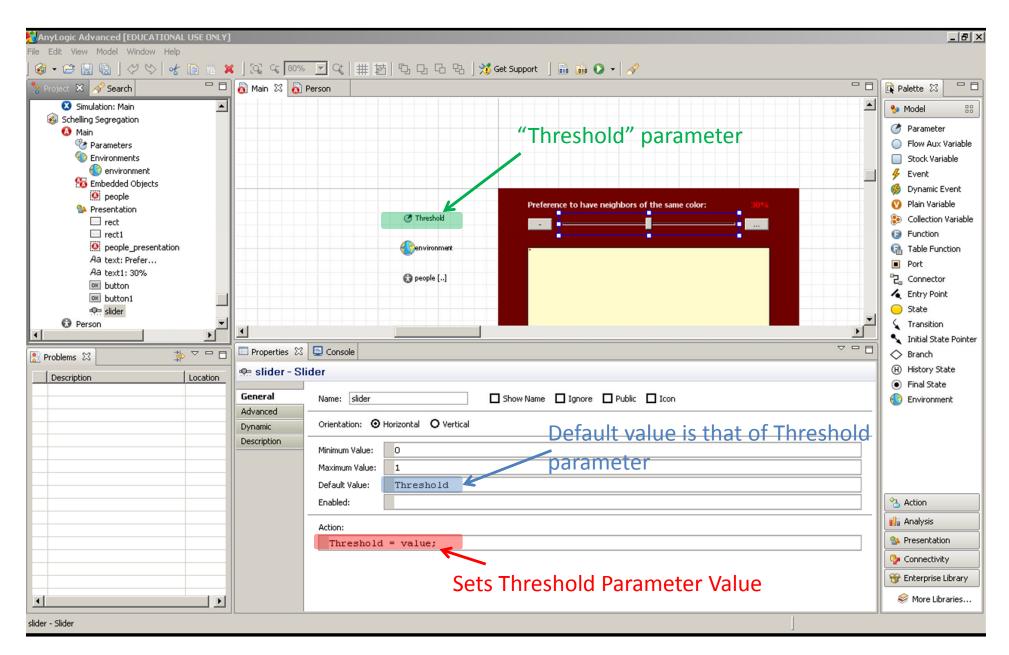
A Discrete Spatial Environment with Random Agent Positioning

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	Description Height: 400 Discrete Cells Columns: 100 Discrete Cells Rows: 100 Neighborhood type: Moore Layout type: Random Network type: User-defined Connections per agent: 2 Connection range: 50 Neighbor link fraction: 0.95	Action Action Analysis Presentation Connectivity Enterprise Library Se More Libraries

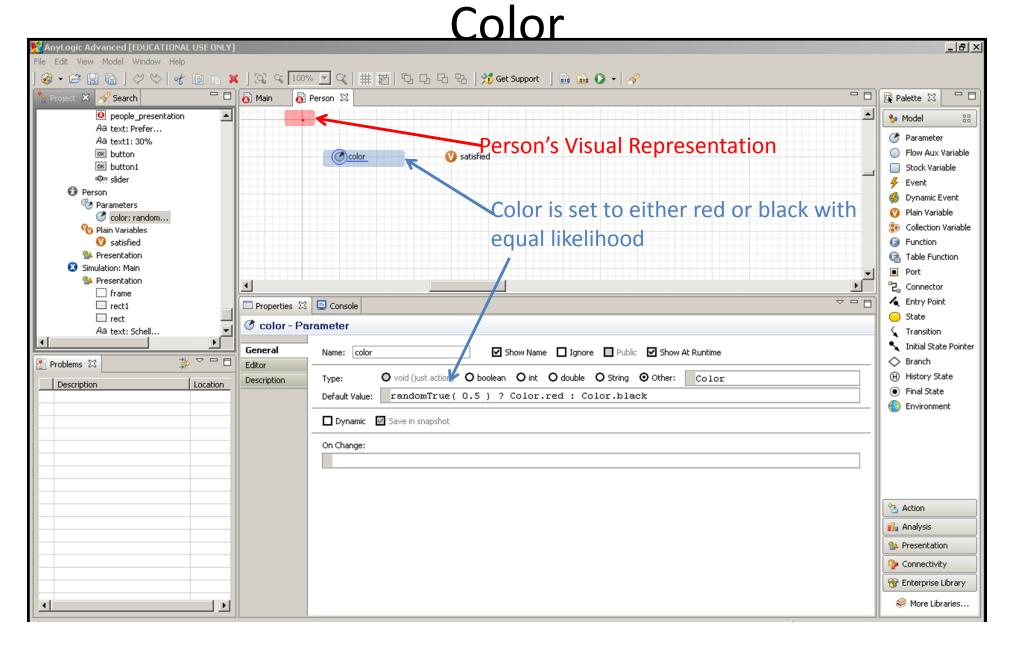
Population Dependence on the Population

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Slider Input Sets Parameter Value



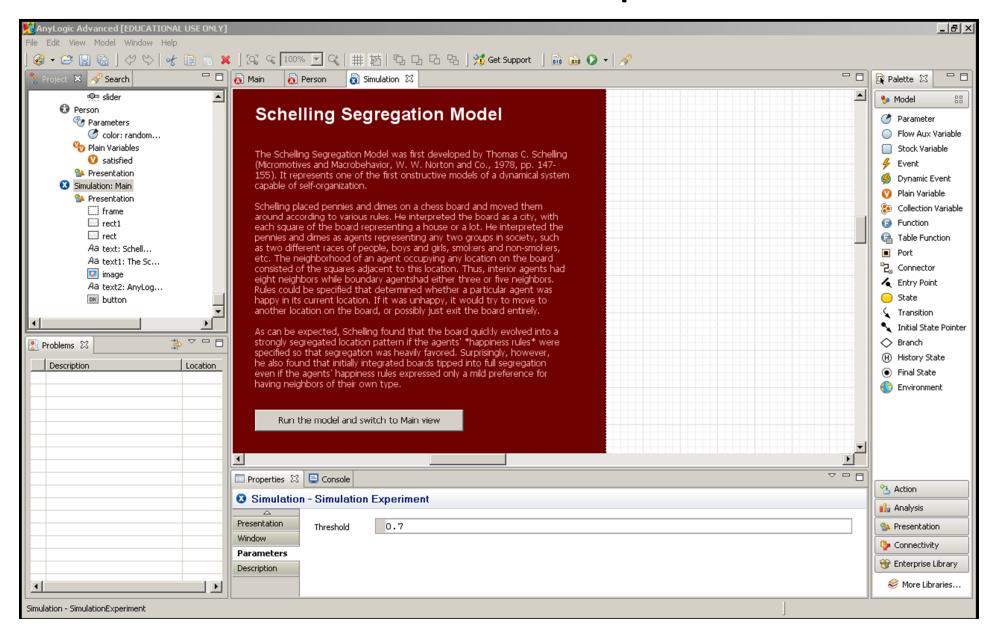
Person is Assigned a Randomly Picked



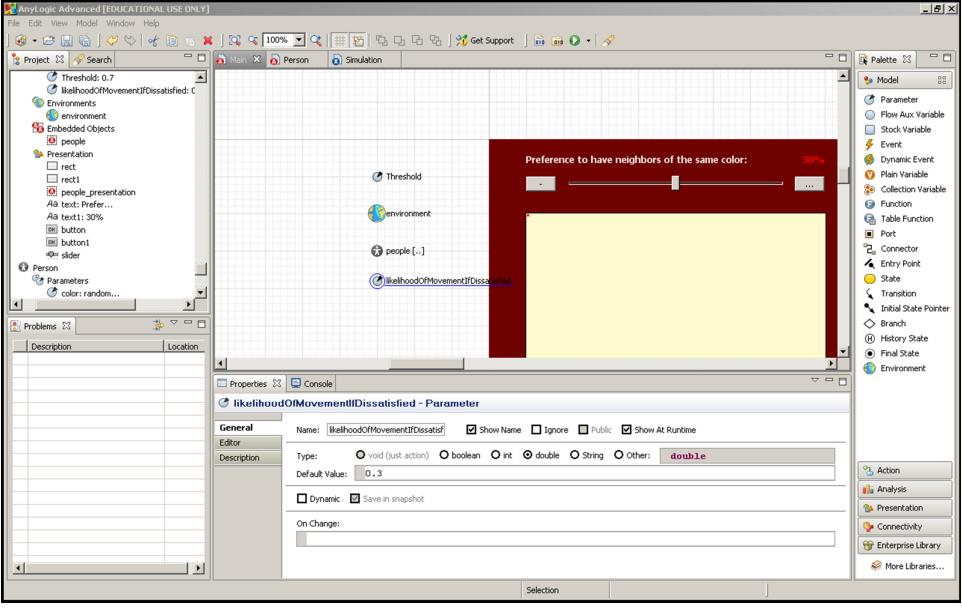
Core Segregation (Movement) Logic

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	On Before Step:	🚯 Environment
Count neighbors	//calc hbow many neighbors have same color as me	
Charing camp colour	int nsame = 0; dept () neighbors = getNeighbors (); Only satisfied if fraction (of 🔰
Sharing same colour	Agencij neighbors - geckerghbors(),	
(should be in diff.	satisfied = true; //no neighbors is good too Suffounding IndividualS	
	Sharing color exceeds	
Function).	for (Agent a : neighbors)	Action
	if(((Person)a).color.equals(color)) threshold	👔 Analysis
	nsame++;	
	//satisfied if percent of same color is greater than a given threshold	
	<pre>satisfied = nsame >= get_Main().Threshold * neighbors.length;</pre>	Connectivity
	On Step: if dissatisfied,	😚 Enterprise Library
	if(! satisfied && randomTrue(0.3))	🖉 More Libraries
	jumpToRandomEmptyCell(); 30% chance of moving	

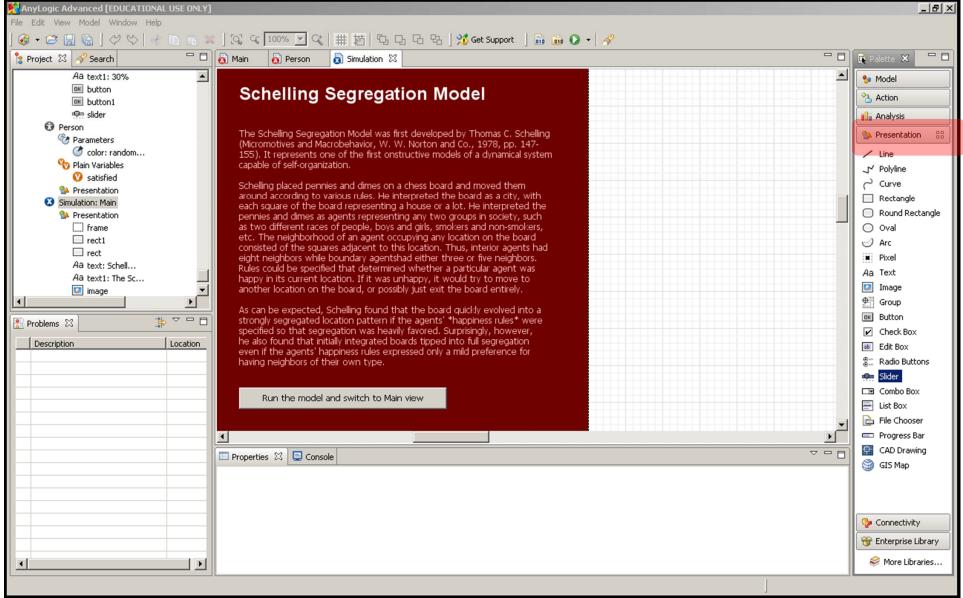
Experiment: Simulation Sets Parameter Assumptions



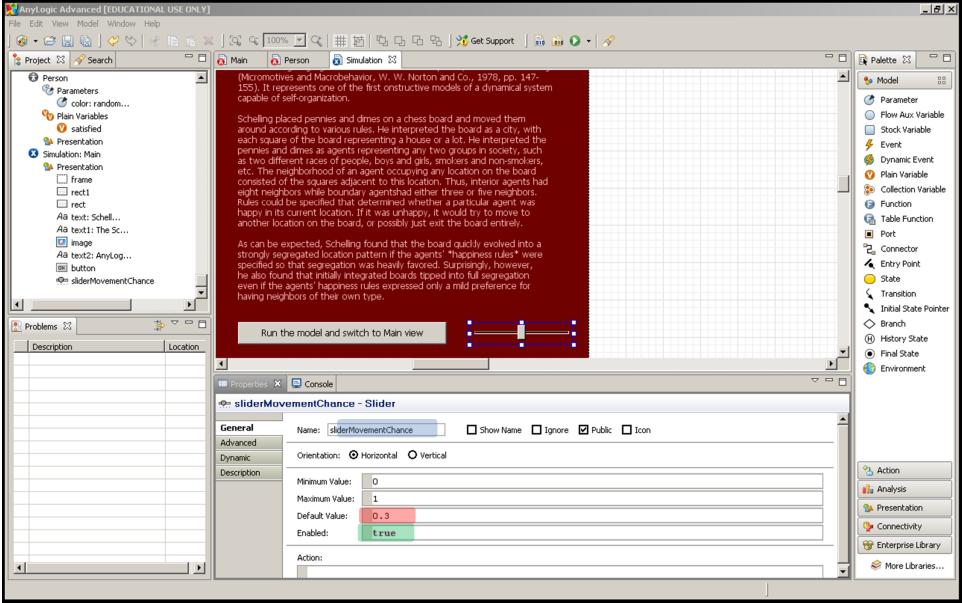
Add a Parameter to Main



Experiment: Add a Slider!



Setting the Slider Properties



Setting Value for Parameter from Slider

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	Simulation - Simulation Experiment General Name: Simulation Main active object class (root): Main Ignore	
	Window Image: Treated seed (unique simulation runs) Window Image: Treated seed (reproducible simulation runs) Seed Value: 1	Action
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Modify Person's Behavior to Depend on New Parameter

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	Parameters Description	nsame++;	n)a).color.equals(color))	Action
		satisfied = nsam	me >= get_Main().Threshold * neighbors.length;	Connectivity
			<pre>&& randomTrue(get_Main().likelihoodOfMovementIfDissatisfied)) mEmptyCell();</pre>	 Enterprise Library More Libraries.

Movement in Discrete Space

- jumpToCell(int row, int column)
 - Jumps to a particular unoccupied cell
 - Precondition: destination cell is unoccupied
- moveToNextCell(int direction)
 - Moves agent into neighbouring cell in a given direction
 - Directions: NORTH, SOUTH, EAST, WEST, NORTHEAST, NORTHWEST, SOUTHEST, SOUTHWEST
 - Precondition: destination cell is unoccupied
- jumpToRandomEmptyCell
 - Jumps to randomly selected empty cell (returning true), returns false if no empty cell can be located

Discovery in Discrete Space

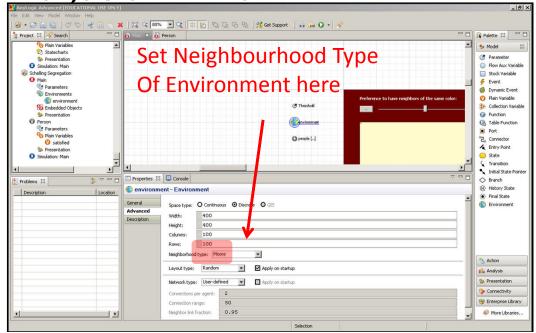
- int []findRandomEmptyCell
 - Returns row & column of an unoccupied cell
- Getting agents in cell or direction
 - getAgentAtCell(int row, int column)
 - getAgentNextToMe(int direction)
 - getNeighbors()

Neigbourhood Models

Moore: Cardinal directions

– NORTH,SOUTH,EAST, WEST

- Euclidean
 - NORTH, SOUTH, EAST, WEST, NORTHEAST, NORTHWEST, SOUTHEST, SOUTHWEST



Important Distinction

- Suppose an agent is moving in discrete 2D space and need to be concerned about moving into the same cell as another agent
- We can readily prevent this agent from moving into another cell currently occupied
- But canwe prevent this agent from colliding with another agent that wishes to move into the same cell?
 - To answer this, we need to be clear about the model of time used by agents

Two Key Models of Time in Anylogic: Synchronous Time

- Here, agents all change in lockstep, separated by fixed "time steps"
- When computing agent behavior (to determine agent state in the next timestep), our enquiries about agent state (e.g. using *getAgentAtCell* or *getAgentNextToMe*) need to ask about the situation in the current timestep
 - We gather needed information regarding current state in "onBeforeStep", and changes are performed in "OnStep".
- This is similar to what we saw in System Dynamics the changes over the next small interval of time (Δt) depend on the current value of the stocks
 - These changes are then applied at once, and all stocks are updated

Enabling Synchronous Time

- Unless enable the steps, the various handlers for synchronized time (e.g. "On before step", "On step", "On after step") etc.) are executed
 - Both environment and agents have "On before step" and "On after step" handlers
 - "On before step" for environments is executed before the corresponding method for agents
 - "On after step" for environments is executed after the corresponding method for agents
- Synchronous time can be enabled via the environment "General" page
 - Click checkbox "Enable steps"

Two Key Models of Time in Anylogic: Asynchronous Time

- Here, every agent is updated at a different time
- No two agents are typically likely to be updated at exactly the same time, so when considering the state of other agents they "see" the last situation where the other agent has been updated

Synchronization & Discrete Agent Movement

- In Synchronous mode, it is difficult to know if two agents will collide using data on the current timestep
 - Even if we know where the other object was during the current timestep, it's possible it will move into the cell we wish to occupy in the next timestep
- It is simpler to handle this asynchronously
 - Here, we can have each agent update at slightly different times, and observe the location of the other agents at the current time – without any significant chance that they will move to the same place at the same time.
- This issue only arises for discrete agent movement, as this is the only case where cells only contain 1 agent